

17-18th November, Niš, Serbia

FINAL PROGRAM

SESSIONS OVERVIEW

	Thursday, November 17, 2022		
Time	Activities	Place	
10:30 – 11:00	Registration	Lobby D	
11:00 – 11:30	Opening Ceremony	Room 1	
11:30 – 12:15	Welcome Cocktail	Faculty Restaurant	
12:15 – 13:15	Plenary Session	Room 1	
13:15 – 13:30	Break		
13:30 – 15:00	Session A: Information and Communication Technologies	Room 1	
13:30 – 15:00	Session B: Measurements & Instrumentation, Applied Mathematics	Room 2	
15:00 – 16:30	Session C: Manufacturing and Information Technologies	Room 1	
15:00 – 16:30	Session D: Mechatronics and Robotics	Room 2	
19:00	Conference Dinner		

Friday, November 18, 2022		
Time	Activities	Place
10:00 - 11:30	Session E: Artificial Intelligence and Machine Learning	Room 1
11:30 – 13:00	Session F: Renewable and Non-Conventional Energy Sources	Room 1
13:00 – 15:00	Project Session : ERASMUS + and H2020 projects presentation	Room 1
15:00	Conference Closing	

All sessions will be held at the <u>Faculty of Electronic Engineering in Niš</u>, street Aleksandra Medvedeva 14, 18000 Niš (<u>https://goo.gl/maps/NhdxL8KzsaxeScQt7</u>)

 $Lobby\ D-Lobby\ is\ located\ in\ front\ of\ the\ Dean$'s office

Room 1 – Congress hall is located on the left side before Dean's office

Faculty Restaurant – next to the Room 1

Room 2 - floor M1, between Faculty library and Room 1



CONTENT

Thursday 17th November 2022

<u>Plenary Session</u> <u>Thursday, 17th November, 12:15 – 13:15 (local time)</u>				
Plenary Session	P1 ● Invited paper			
	SD. Stan, A. Plesa, and E. Teutan			
Kinematics Si	Kinematics Simulation and Analysis in MATLAB/Simscape for a Class of 2-DOF Parallel Robots			
Plenary Session	P2 ● Invited paper			
	S. Šprager and K. Benkič			
Metrel Clou	Metrel Cloud – R&D Challenges Towards the Most Convenient Way to Achieve Efficient Connectivity			
Plenary Session	P3 ● Invited paper			
	nnić, M. Simonović, L. Stojanović, D. Rangelov, A. Miltenović, and M tal Twin-Based Unmanned Outdoor Field Robots Lightweigh			

Session A – Information and Communication Technologies Thursday, 17 th November, 13:30 – 15:00 (local time)			
	Chairperson: Dragan Stojanović		
Session A	A1 ● Regular paper		
	A. Stojnev Ilić, D. Stojanović, N. Stojanović, and M. Ilić		
\mathbf{A}]	Big Data System Architecture for Adaptive Streaming Data Analyt	ics	
Session A	A2 ● Regular paper		
	K. Benkič, B. Cigale, and S. Šprager		
	Could Over-Protecting a Web Service be Counter-Effective?		
Session A	A3 ● Regular paper		
A. Par	najotović, J. Anastasov, A. Cvetković, D. Milić, D. Milović, and A. Laz	arević	
Outage Perfor	Outage Performance Analysis of a Two-User Uplink NOMA Scenario Over Fisher-Snedecor F Fading Channels		
Session A	A4 ● Regular paper		
I. Kocić, D. Mitić, N. Danković, S. Nikolić, N. Jotović, and P. Đekić KEPServerEX as a Data Collection Tool for Process Identification			



Session A	A5 ● Regular paper		
	B. Cigale		
Microcontrolle	Microcontroller Shortage: Lessons Learned in the Firmware Porting in the Company Metrel d.d.		
Session A	A6 ● Regular paper		
N. Petrović			
Semantic Approach to Code Quality Improvement in DevOps			

Thursday, 17 th November, 13:30 – 15:00 (local time)		
	Chairperson: Saša S. Nikolić	1
Session B	B1 ● Regular paper	
	S. Đorđević and M. Simić	
Non-	Intrusive Appliance Load Monitoring Using Current Harmonic Pl	nasor
Session B	B2 ● Regular paper	
	M. Pejović	
Characteriz	ation of Commercial Gas-Filled Surge Arresters Using Systems for Measurement and Acquisition of Data	r Automatic
Session B	B3 ● Regular paper	
	A. Đorđević, M. Milovanović, M. Milojković, and M. Spasić	
Intelligent C	lassification of Environmental Conditions Influencing the Work of Equipment	Laboratory
Session B	B4 ● Regular paper	
Session B	J. Nedeljković, G. Nikolić, and M. Stojčev	
Session B	J. Nederjkovie, G. Mikolie, and M. Stojeev	
	ge Based Data Compression Technique for Saving Values in Data I	Logger
	3	Logger
Averaş	ge Based Data Compression Technique for Saving Values in Data I	Logger
Averaş Session B	ge Based Data Compression Technique for Saving Values in Data I B5 • Regular paper	
Averaş Session B	ge Based Data Compression Technique for Saving Values in Data I B5 • Regular paper P. Rajković, S. Marinković, and M. Stanković	



Session C – Manufacturing and Information Technologies Thursday, 17 th November, 15:00 – 16:30 (local time) Chairperson: Ivan Ćirić		
	Joanna Alexieva , Pancho Tomov, and Lubomir Dimitrov	
	Influence of ISO 27001 on the Execution of the Strategic Goals	
Session C	C2 • Regular paper	
	A. Kitić and M. Radišić	
	Trends in the Financing of Innovative SMEs in Serbia From Gran	ts
Session C	C3 • Regular paper	
	D. Ćirić, M. Ivanović, G. Jović, F. Pešić, and M. Mijajlović	
Application of	he Quality Function Deployment Method in the Mechanical Struct Two-Roll Rubber Mill Frame	ure Design of the
Session C	C4 • Regular paper	
	D. Stojiljković, I. Ćirić, N. T. Pavlović, N. Ivačko, and D. Jevtić	
	Influence of FDM Parameters on Flexure Hinges Properties	
Session C	C5 ● Regular paper	
	S. Stamenković, S. Ranđelović, and N. Kostić	
	FEM Analysis Stress Strain state at Deep Drawing	
Session C	C6 • Regular paper	
V. M	iltenović, Z. Nikolić, M. Milojković, S. Perić, M. Milovanović, and M.	Spasić
Role an	d Importance of Digital Technologies in the Development of Smart	Products

Session D – Mechatronics and Robotics Thursday, 17 th November, 15:00 – 16:30 (local time)		
	Chairperson: Emina Petrović	
Session D	D1 ● Regular paper	
	EG. Tulcan, C. Sticlaru, and EC. Lovasz	
De	esign of a Novel Medical Disinfection Robot with Folding Mechanis	sm
Session D	D2 ● Regular paper	
	M. Tomić, M. Banić, M. Simonović, and M. Milošević	
Navigat	ion of the Skid Steering Physically Connected off-Road Robotized	Vehicles
Session D	D3 ● Regular paper	
A. Tomović, J. Jovanović, M. Damjanović, and R. Tomović		
The Enclosure of Research on the Impact of Reduction of Unbalance on the Intensity of Vibrations of a Rigid Rotor Supported on Radial Active Magnetic Bearings		



Session D	D4 ◆ Regular paper	
	A. Leshchev-Romanenko and S. Saidov	I.
Motion Planning of a Wheeled Robot in a Flat Dynamic Uncertain Environment Using Hybrid Motion Planning Algorithm Based on A* and Artificial Potential Field Method		
Session D	D5 ● Regular paper	
	J. Erić Obućina, S. Stankovski, G. Ostojić, and S. Aleksandrov	
Modeling A	nd Simulation of The Hydraulic System with Installing a Frequenc	y Converter
Session D	D6 ● Regular paper	
	M. Novaković, V. Reljić, M. Šešlija, V. Mladenović, and Z. Jovanović	
	Reuse of Exhausted Air in Closed Pneumatic Circuit	

Friday, 18th of November

Session E – Artificial Intelligence and Machine Learning Friday, 18 th November, 10:00 – 11:30 (local time) Chairperson: Dejan Milić				
			Session E	E1 • Regular paper
	M. Kostić, S. Đošić, M. Jovanović, and I. Stojanović			
Perfor	mance Analysis of Machine Learning Algorithms for Indoor Local	ization		
Session E	E2 ● Regular paper			
	N. Petrović	l		
Machine Lea	Machine Learning within Information Systems Course using Weka in Java: Monkeypox Case Studies			
Session E	E3 • Regular paper			
I. C	Ćirić, N. Ivačko, Ž. Ćojbašić, M. Pavlović, D. Mitić, S. Lalić, and D. Jev	vtić		
Co	omparison of Simple Object Recognition Algorithms for Robot Visi	on		
Session E	E4 ● Regular paper			
E. Petrovi	c, M. Simonović, V. Nikolić, D. Dimitrijević Jovanović, N. Tomić, and	J. Bijeljić		
Instance Segmen	ntation Using Mask-R-CNN Architecture for Vision Based Inspection Depth	on of Tire Tread		
Session E	E5 ● Regular paper			
S.	Stojanović, D. Antić, M. Milojković, D. Mitić, S. Perić, and S. S. Niko	lić		
Finite-Time Boundedness of Discrete-Time Neural Networks with Norm-Bounded Disturbances and Time-Varying Delays				
Session E	E6 ● Regular paper			
	N. Vukić, S. Perić, D. Antić, D. Mitić, and S. Stojanović	•		
Application of Convolutional Neural Networks for Traffic Sign Recognition for Autonomous Driving System Perception				



Session E E7 ● Regular paper	
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D. Milić, N. Petrović, S. Suljović, R. Stefanović, and V. Vujović

Quantum Machine Learning Approach to QoS Prediction Leveraging Capacity of 5G Wireless System with L-branch SC Combining in Nakagami-m Fading and Nakagami-m Interference Channel

<u>S</u>	<u>Friday</u> , 18 th November, 11:30 – 13:00 (local time)	<u>s</u>
Chairperson: Jasmina Bogdanović Jovanović		
Session F	F1 Regular paper	
	P. Živković, M. Tomić, and B. Radovanović	
S	tudy of Rayleigh-Bénard Convection in a Rectangular Water Tanl	ĸ
Session F	F2 ● Regular paper	
	N. Marković, M. Milošević, and Ž. Ćojbašić	
Intelligent (Control of Heating Tunnel for Improved Performance and Energy	Efficiency
Session F	F3 ● Regular paper	
	M. Jovanović, S. Milanović, and Ž. Spasić	
	Temperature Spatial Modulation in a Slot Fluid Flow	
Session F	F4	
J. Bogdanović	Jovanović, S. Milanović, Ž. Stamenković, M. Jovanović, J. Petrović,	and M. Kocić
Nu	merical Approach to the Calculation of Sprinkler Irrigation System	ms
Session F	F5 ● Regular paper	
M. Nikodijev	vić Đorđević, Ž. Stamenković, J. Petrović, J. Bogdanović Jovanović, a	nd M. Kocić
Control of Nano	ofluid Flow and Heat Transfer in the Horizontal Channel with Por Electric and Moving Magnetic Field	ous Medium by
Session F	F6 Regular paper	
J. Petrović, Ž	Ź. Stamenković, M. Kocić, J. Bogdanović Jovanović, and M. Nikodijev	vić Đorđević
Control of Nar	nofluid Flow and Heat Transfer in the Vertical Channel with Poro Electric and Moving Magnetic Field	us Medium by



Project session Friday, 18th November, 13:00 – 15:00 (local time) Chairperson: Miloš Simonović 1. EU Water Policy and Innovative Solutions in Water Resources Management (INNOWAT), Erasmus+ Jean Monnet Module, 620003-EPP-1-2020-1-RS-EPPJMO-MODULE 2. Transforming Advanced Water Skilling Through the Creation of a Network of Extended-Reality Water Emulative Centres (WATERLINE), HORIZON, 101071306-HORIZON-WIDERA-2021-ACCESS-05 Smart Products and Services Engineering (SPaSE), Erasmus+ Jean Monnet Module, 101047566-3. JMO-2021-HEI-TCH-RSCH 4. The Future is in Applied Artificial Intelligence (FAAI), Erasmus+, 2022-1-PL01-KA220-HED-000088359 5. Instantaneous Infrastructure Monitoring by Earth Observation (IIMEO), HORIZON, HORIZON-CL4-2022-SPACE-01-13: End-to-end earth observation systems and associated services 6. Advanced Integrated Obstacle and Track Intrusion Detection System for Smart Automation of Rail Transport (SMART2), HORIZON, 881784 7. Universal Robotic Platform for Precise Agriculture (AGAR), Innovation Fund of Republic of Serbia and COMING - Computer Engineering d.o.o., 50471 9. Autonomous Trains Undercarriage Visual Inspection System (ATUVIS), Innovation Fund of Republic of Serbia and CAM Engineering, IF 50348 10. Boosting the Scientific Excellence and Innovation Capacity of 3D Printing Methods in Pandemic Period (BRIGHT), Erasmus+, 2020-1-RO01-KA226-HE-095517 11. Collaborative e-platform for Innovation and Educational Enhancement in Medical Engineering (Callme), Erasmus+, 2022-1-RO01-KA220-HED-000087703